

LOW COST COURSE CORRECTION (LCCC) FOR THE M261 HYDRA-70 ROCKET

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Overview

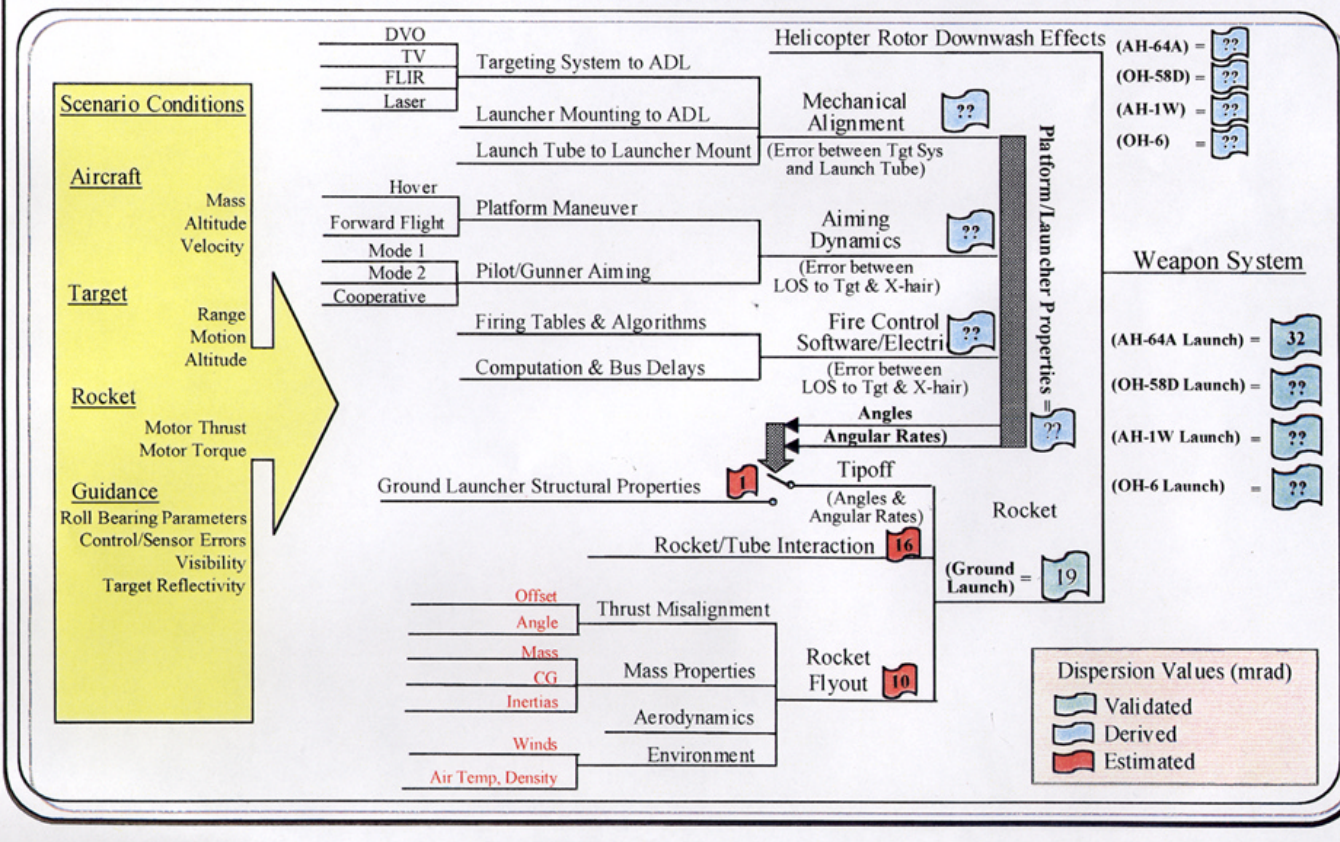
- U.S. Army ARDEC sponsored a study to investigate the feasibility of incorporating Low Cost Course Correction Seeker onto M261, MPSM Rocket
- GD-OTS in conjunction with TG&C Associates and GD-AIS completed study in 2001
- Study Included:
 - M261 LCCC Nose Module Design
 - Aerodynamic Study Results
 - Accuracy Improvement Estimates
 - ARDEC Effectiveness Analysis
- Short range flight testing completed on related LCCC program





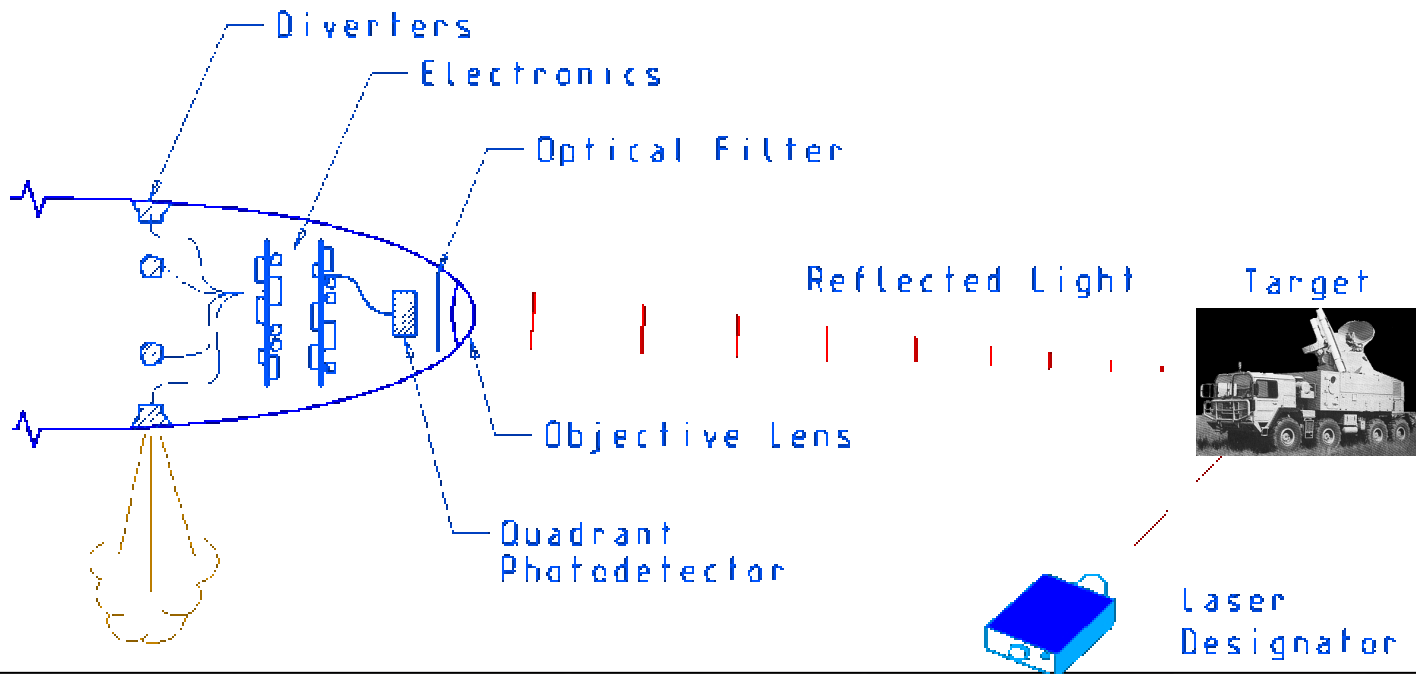
2.75-INCH ROCKET SYSTEM ERROR BUDGET MODELING & SIMULATION

System Error Budget Diagram



24 mrad Systems Error Estimated for M261 Rocket due to Rocket and Platform Induced Errors

Low-Cost Guidance Approach



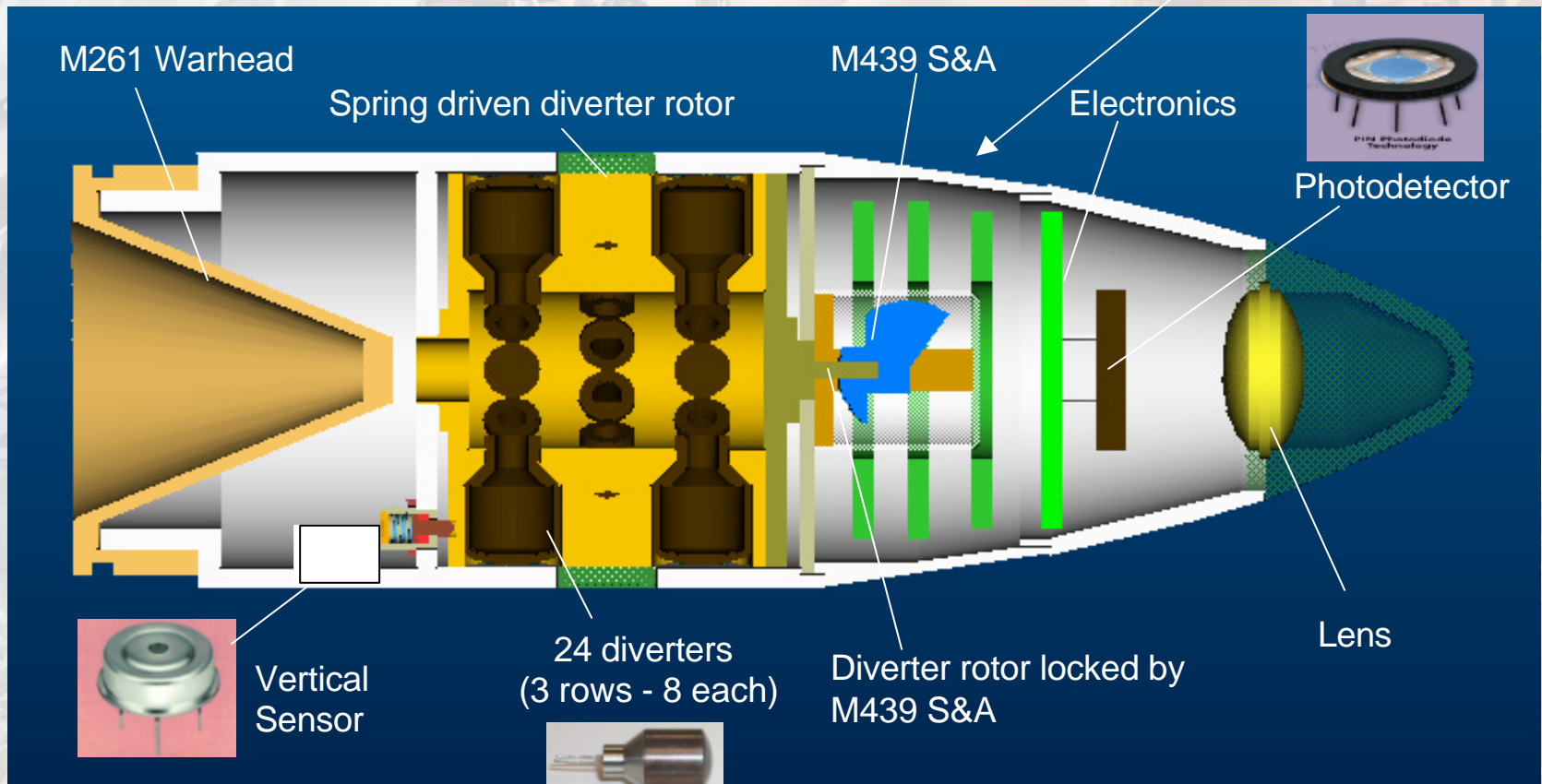
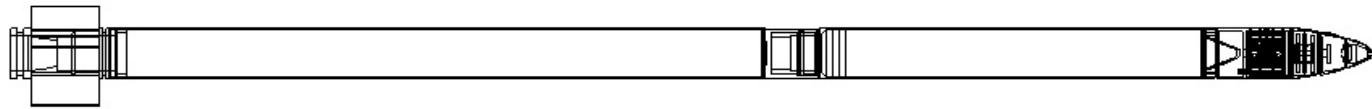
- Body fixed guidance approach eliminates system errors to make ammunition much more accurate and effective
- Semi-active laser guidance with micro explosive diverter control system
- Eliminates need for expensive rate sensors and gyros
- Unnecessary to train and develop complex algorithms
- Off the shelf electronic components

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M261 2.75" LCCC TACTICAL MODULE DESIGN



LCCC NOSE MODULE CAN BE USED ON EXISTING M261 ROCKETS

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M261 Aerodynamic Study Parameters

- LCCC System Simulation Parameters

Parameter	Value
Impulse	2.6 N-s
Pulse Duration	0.5 msec
No. of Diversers	32 (2 rows of 16 diversers)
Divert Axial Location	0.6825 m (fwd of initial CG location)
Phase Angle Tolerance	1.0 Deg
Azimuth Error (@launch)	24 mrad
Launch Altitude	10 m
Mass Properties	M261 Round

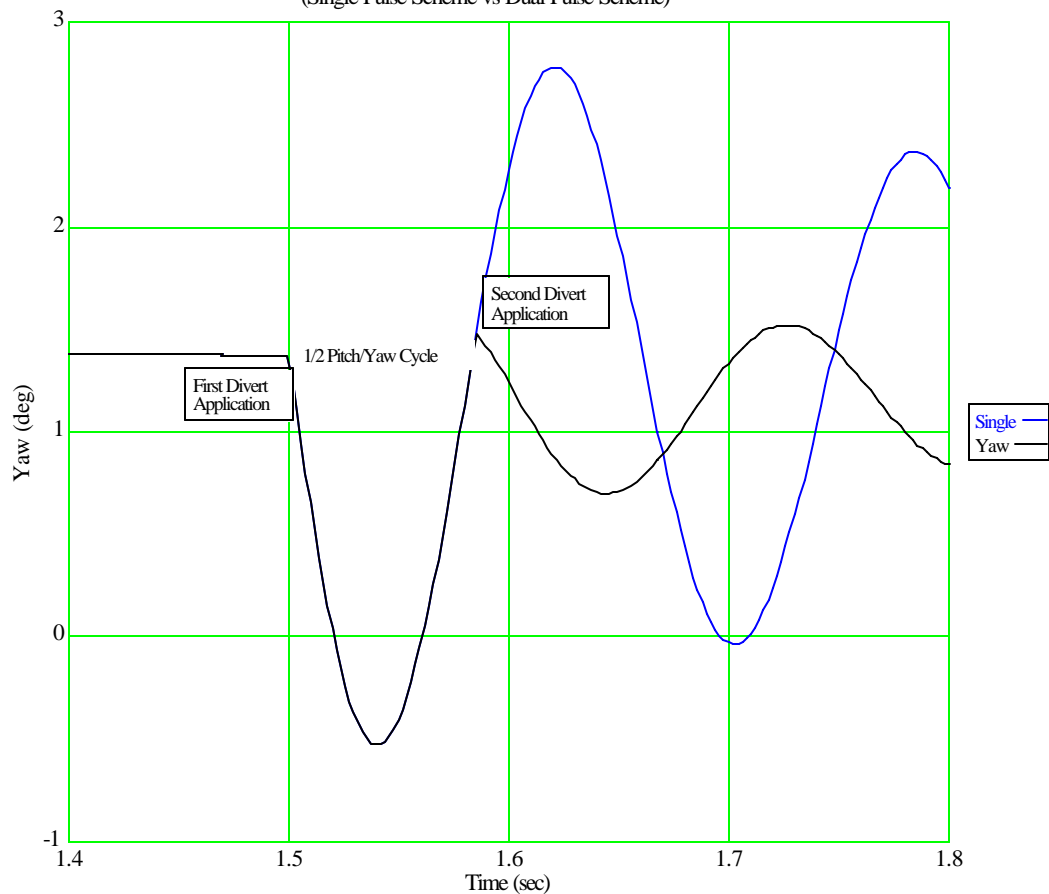
- All performance evaluation based on a target located on the ground 2-6km downrange of the launch point.

Control Algorithm Definition/Selection

- Dual Pulse Control Law Approach

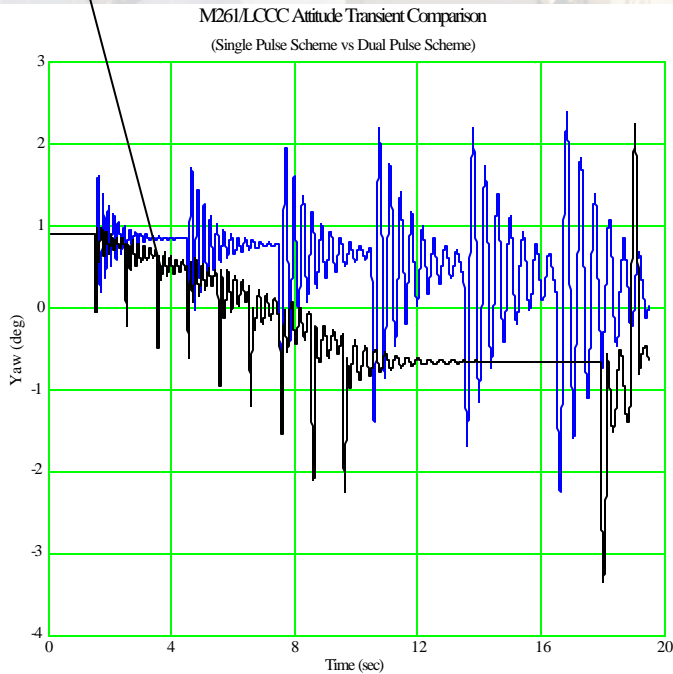
M261/LCCC Attitude Transient Comparison

(Single Pulse Scheme vs Dual Pulse Scheme)

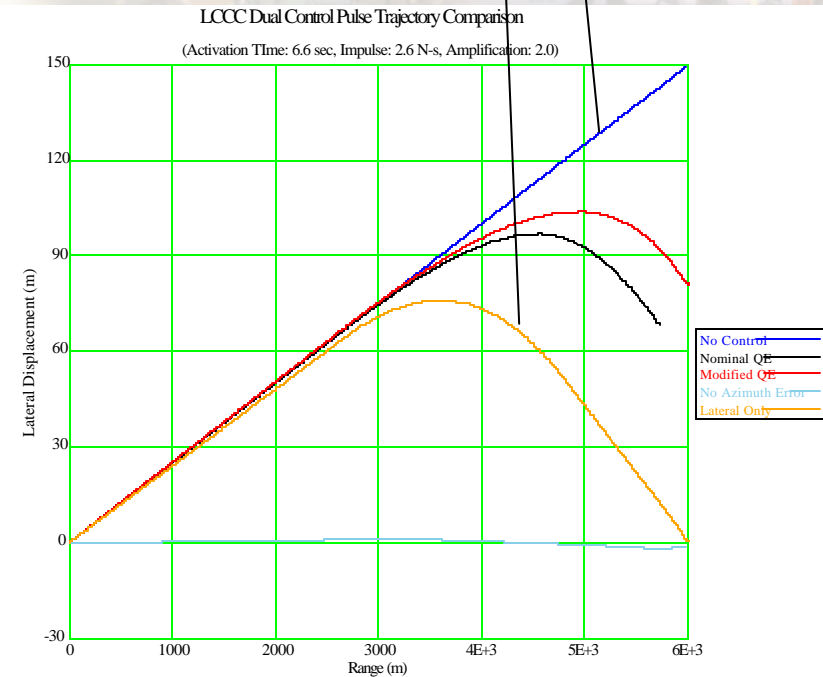


2.75" Modeling Results 6 KM

Dual Divert Provided Best
Accuracy Improvement for 2.75"
Rocket



11 Pairs of 2.6 N-Sec Diverters
provides 0.5 mrad accuracy
compared with 24 mrad baseline



Single vs. Dual Divert Approach

Accuracy Improvement Quantified

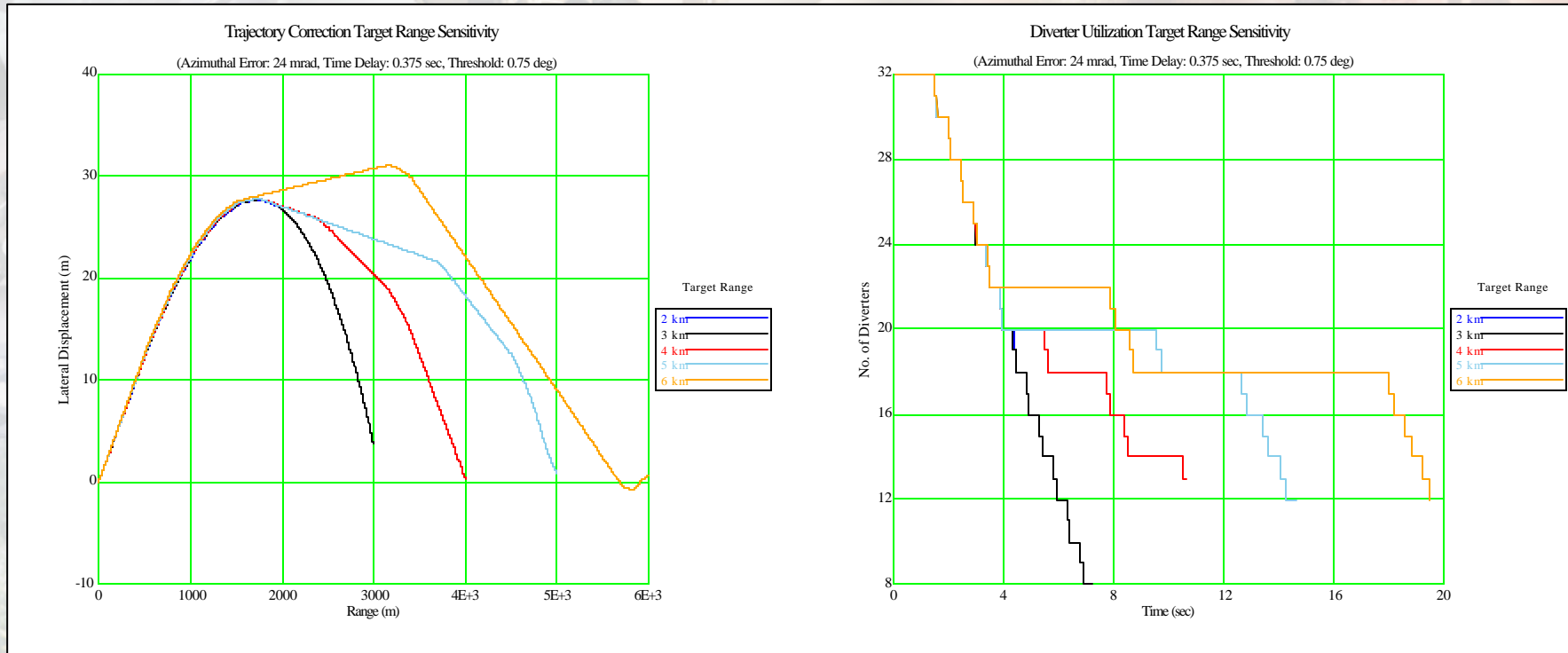


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2.75" Modeling Results 2-6 KM

Simulation Results



- Lateral dispersion < 5 m for the range of target locations of 3 km and longer



LCCC M261 Accuracy Improvement

Case 3

11 Pairs 5.2 N-sec diverters
Up/down sensor
(± 1 sigma = 6 M)

Case 1

11 Pairs 2.6 N-sec diverters
No Up/down sensor
(± 1 sigma = 156 M)

Baseline

No Correction
(± 1 sigma = 288 M)



INITIAL CONDITIONS
Launch Error: 24 mrad

ALTITUDE
(Z)

RANGE
(X)

Uncorrected
 ± 18 Dispersion
(66%)

AZMIUTH
(Y)

288 M

6 KM

Case 2

11 Pairs 2.6 N-sec diverters
Vertical sensor
(± 1 sigma = 12 M)

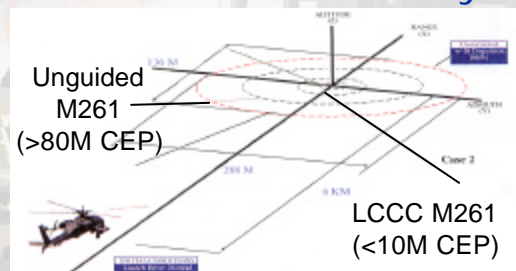
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M261 EFFECTIVENESS ANALYSIS

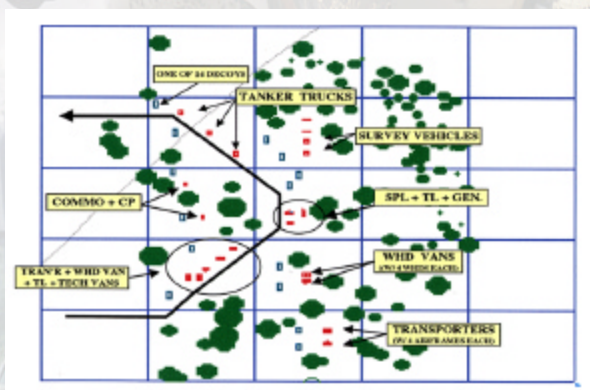
Increased Accuracy



P_{HIT}		
Range	M261	LCCC M261
6 KM	.07	.97

WARFIGHTER BENEFITS

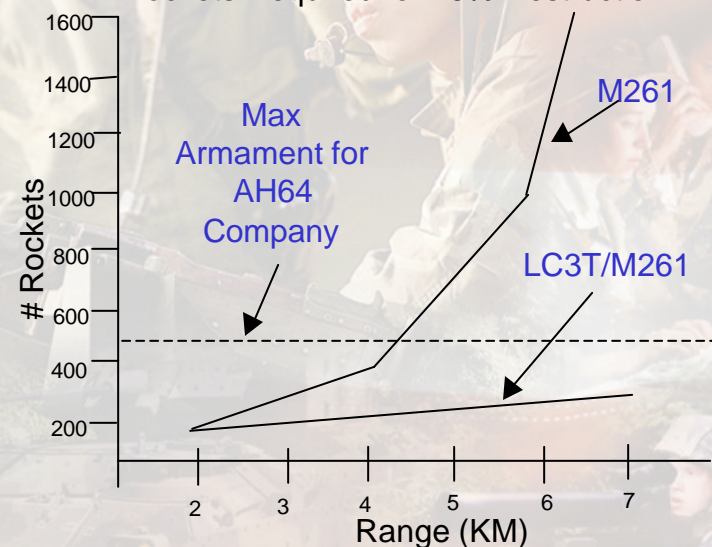
Against Scud Battery



Attack	Helicopter	Weapon	Percent Destruction
(6) AH64	50% Load	M261	.30
30-60 hr Time delay			
(6) AH64	50% Load	LC3T/M261	.60
48 hr Time delay			

Against Dismounted NKPA Motorized Infantry

Rockets Required for 45% Destruction



ARDEC Effectivity Analysis Shows Warfighter Benefits of LCCC M261 Rocket

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Demonstration Testing

LED Target
(40' to side of target)



GD-OTS OTI Rest Range

Multi-Layered Soft Catch
Target

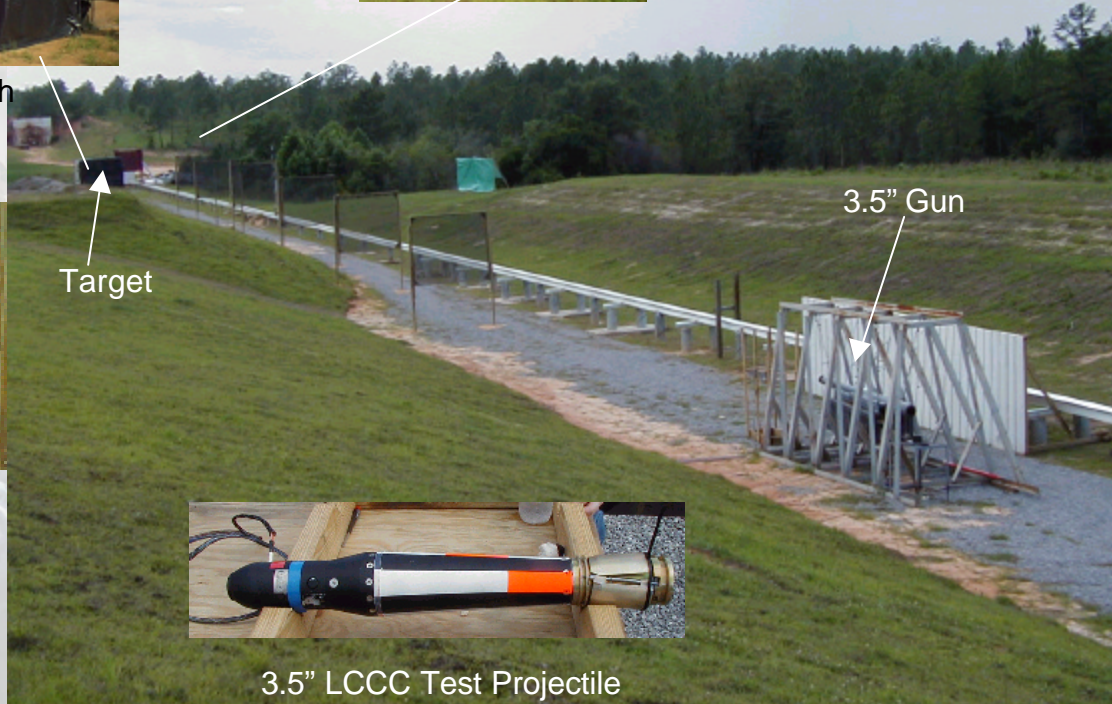


Target



Projectile Soft Catch in
Rubber Filled Target

3.5" Gun



3.5" LCCC Test Projectile

Short Range Testing Demonstrated LCCC Guidance Approach Feasibility
(Acquired Target & Diverted Projectile toward target)

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Summary

- Significant accuracy improvement (from 24 mrad to 1 mrad) appears achievable with body fixed semi-active laser guidance approach
- Dual pulse thruster approach and vertical sensor required for optimum accuracy improvement
- ARDEC effectivity analysis shows great benefit for improved accuracy M261 rocket
- Testing conducted under 2001 ARDEC Tech Base Program has shown feasibility of approach for guiding spinning projectiles
- Hardware in the Loop and Flight testing required to quantify accuracy improvement achievable with LCCC

